

Discrete Choice in the Presence of Numerical Uncertainties

How often does your program make a wrong decision?



MAX PLANCK INSTITUTE
FOR SOFTWARE SYSTEMS



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POLYTECHNIQUE
UNIVERSITÉ PARIS-SACLAY

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EMSOFT 2018

Programming with Numerical Uncertainties

```
def controller(x:Real, y:Real, z:Real):Real={  
    val res = -x*y - 2*y*z - x - z  
    return res  
}
```

- **Reals** are implemented in Floating point/ Fixed point data type

Programming with Numerical Uncertainties

```
def controller(x:Float32, y:Float32, z:Float32):Float32={  
    val res = -x*y - 2*y*z - x - z  
    return res  
}
```

- Reals are implemented in Floating point/ Fixed point data type
- Introduces round-off error

State of the Art: Round-off Error Analysis

```
def controller(x:Float32, y:Float32, z:Float32):Float32={  
  val res = -x*y - 2*y*z - x - z  
  return res  
}
```

Computes **sound absolute error bound** in the
worst case

Programs with Discrete Decisions

```
def controller(x:Float32, y:Float32, z:Float32):Float32={  
  val res = -x*y - 2*y*z - x - z  
  if (res <= 0.0)  
    raiseAlarm()  
  else  
    doNothing()  
}
```

Programs with Discrete Decisions

```
def controller(x:Float32, y:Float32, z:Float32):Float32={  
  val res = -x*y - 2*y*z - x - z  
  if (res <= 0.0)  
    raiseAlarm() → real valued program  
  else  
    doNothing() → finite precision program  
}
```

A program can make a **wrong decision** due to **numerical uncertainties!**

Our Goal

```
def controller(x:Float32, y:Float32, z:Float32):Float32={  
  val res = -x*y - 2*y*z - x - z  
  if (res <= 0.0)  
    raiseAlarm()  
  else  
    doNothing()  
}
```

Compute **how often** does your program make a **wrong decision**?

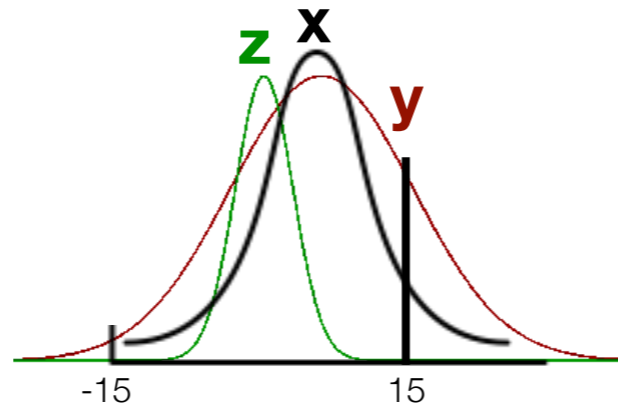
Worst Case Analysis is not enough!

```
def controller(x:Float32, y:Float32, z:Float32):Float32={
  val res = -x*y - 2*y*z - x - z
  if (res <= 0.0)
    raiseAlarm()
  else
    doNothing()
}
```

- A program **always** takes the wrong path in the **worst case**
- Consider the **probability distributions** of inputs

Input distributions are important!

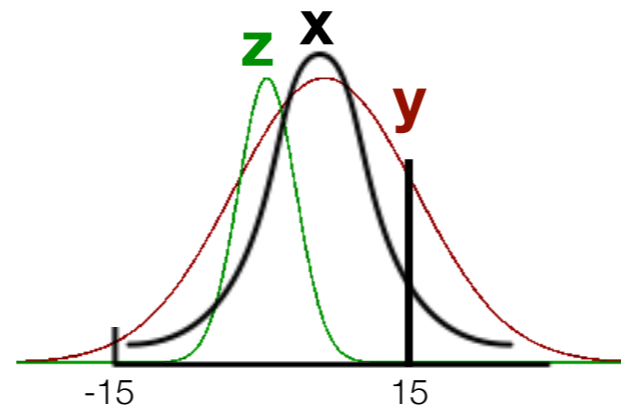
```
def controller(x:Float32, y:Float32, z:Float32):Float32={  
  require (-15.0 <= x, y, z <= 15.0)
```



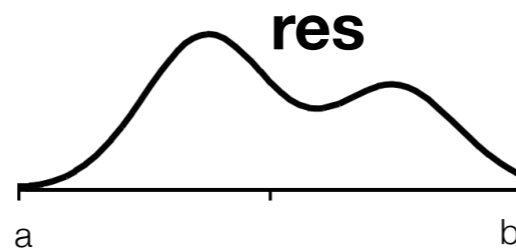
```
  val res = -x*y - 2*y*z - x - z  
  if (res <= 0.0)  
    raiseAlarm()  
  else  
    doNothing()  
}
```

Input distributions are important!

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```



```
  val res = -x*y - 2*y*z - x - z
```

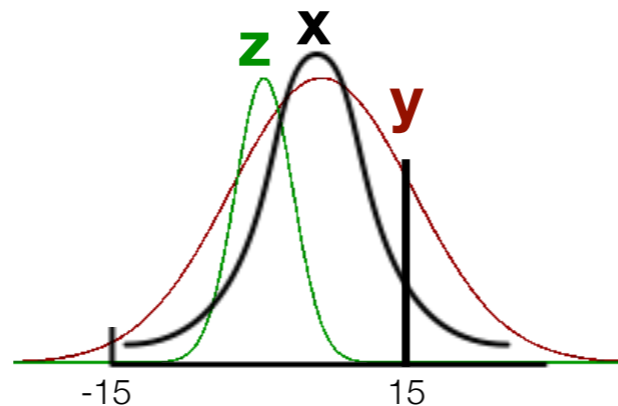


```
  if (res <= 0.0)  
    raiseAlarm()  
  else  
    doNothing()
```

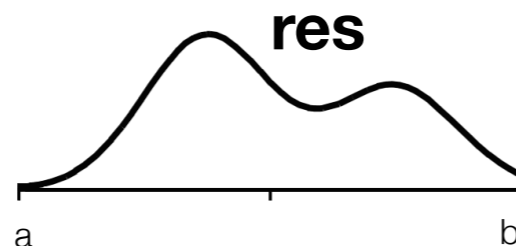
```
}
```

Input distributions are important!

```
def controller(x:Float32, y:Float32, z:Float32):Float32={  
  require (-15.0 <= x, y, z <= 15.0)
```



```
  val res = -x*y - 2*y*z - x - z
```



```
  if (res <= 0.0)  
    raiseAlarm()  
  else  
    doNothing()  
}
```

}

How often?

Compute **Wrong Path Probability**

Contributions

Sound analysis of numerical uncertainties on decisions

Evaluation on embedded examples

Prototype implementation in Daisy



<https://github.com/malyzajko/daisy/tree/probabilistic>

Overview: Sound Analysis

**Finite Precision
Program with
Probabilistic Inputs**

**Wrong Path
Probability (WPP)**

Overview: Sound Analysis

Finite Precision
Program with
Probabilistic Inputs

Round-off Error
Analysis

Wrong Path
Probability (WPP)

Overview: Sound Analysis

Finite Precision
Program with
Probabilistic Inputs

Round-off Error
Analysis

$e = 0.01$

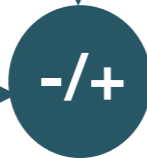
Wrong Path
Probability (WPP)

Overview: Sound Analysis

Finite Precision
Program with
Probabilistic Inputs

Round-off Error
Analysis

Decision
Threshold (T)



e

Wrong Path
Probability (WPP)

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Decision
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-/+

e

```
if (res <= 0.0) raiseAlarm()  
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Wrong Path
Probability (WPP)

Overview: Sound Analysis

Finite Precision
Program with
Probabilistic Inputs

Round-off Error
Analysis

Decision
Threshold (T)

$T = 0.0$

-/+

```
if (res <= 0.0) raiseAlarm()  
else doNothing()
```

Critical Interval
 $[T-e, T+e]$

Wrong Path
Probability (WPP)

Overview: Sound Analysis

Finite Precision
Program with
Probabilistic Inputs

Round-off Error
Analysis

$$e = 0.01$$

Decision
Threshold (T)

-/+

$$T = 0.0$$

$$[0.0 - 0.01, 0.0 + 0.01]$$

Critical Interval
[T-e, T+e]

Wrong Path
Probability (WPP)

Overview: Sound Analysis

Finite Precision
Program with
Probabilistic Inputs

Round-off Error
Analysis

Distribution
Propagation

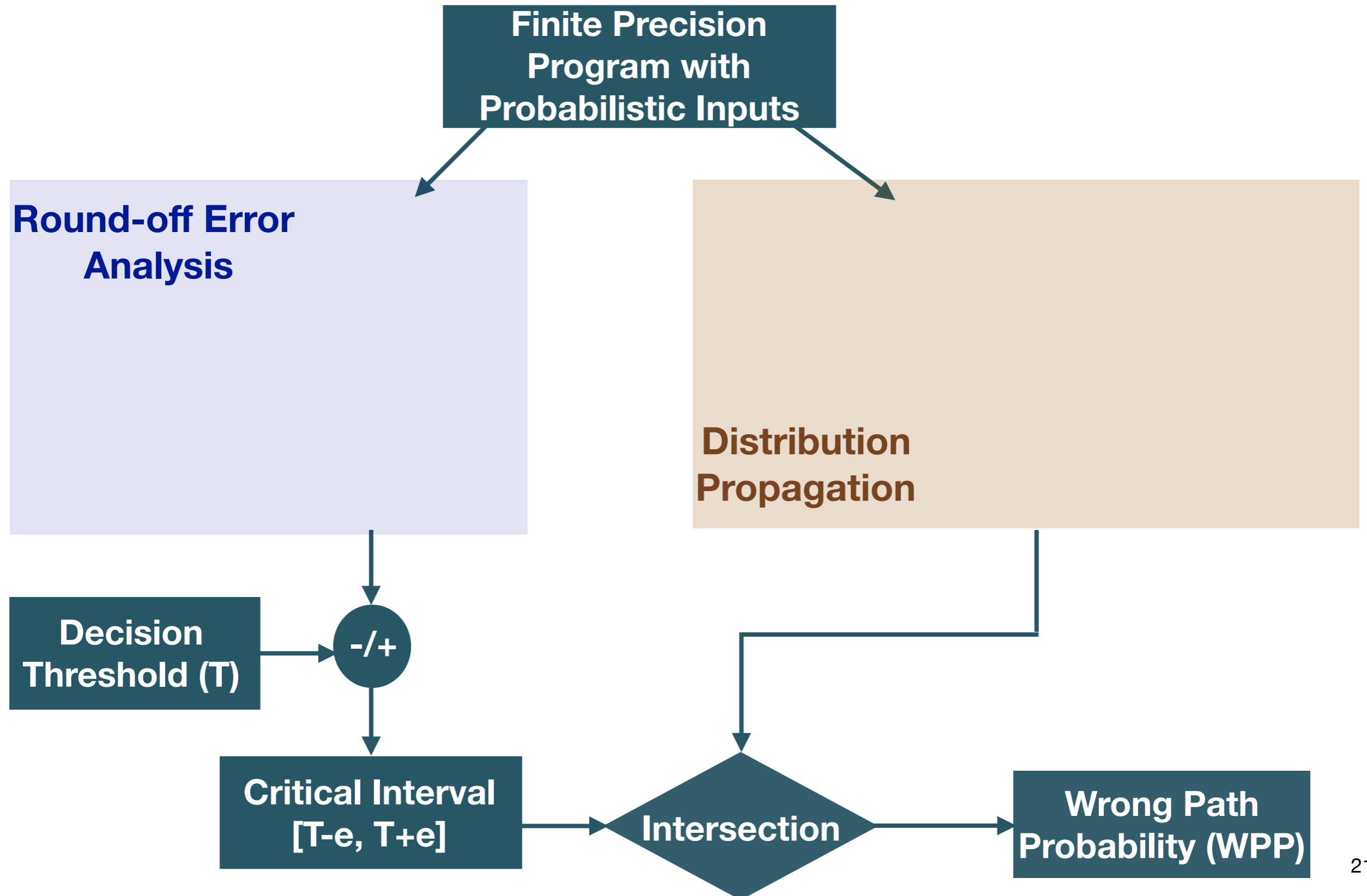
Decision
Threshold (T)

-/+

Critical Interval
[T-e, T+e]

Wrong Path
Probability (WPP)

Overview: Sound Analysis



Round-off Error Analysis

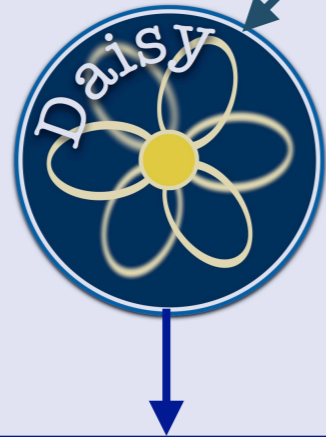
Finite Precision
Program



Round-off
Error (ϵ)

Round-off Error Analysis

Finite Precision Program

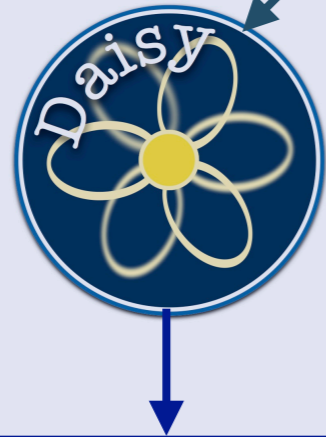


Round-off Error (e)

```
def controller(x:Float32, y:Float32, z:Float32): Float32 = {  
  require (-15 <= x, y, z <= 15)  
  val res = -x*y - 2*y*z - x - z  
}
```

Round-off Error Analysis

Finite Precision Program

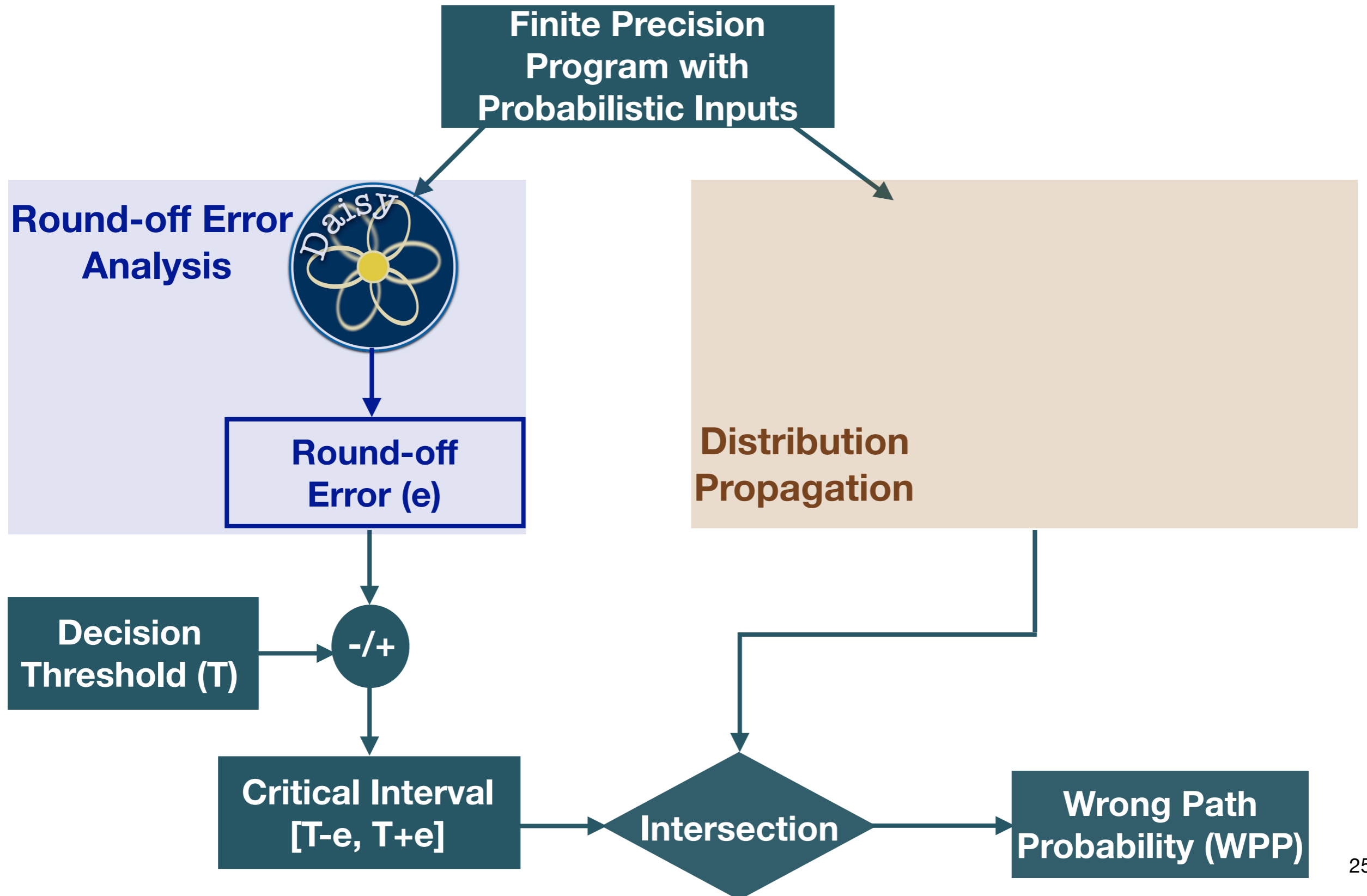


Round-off Error (e)

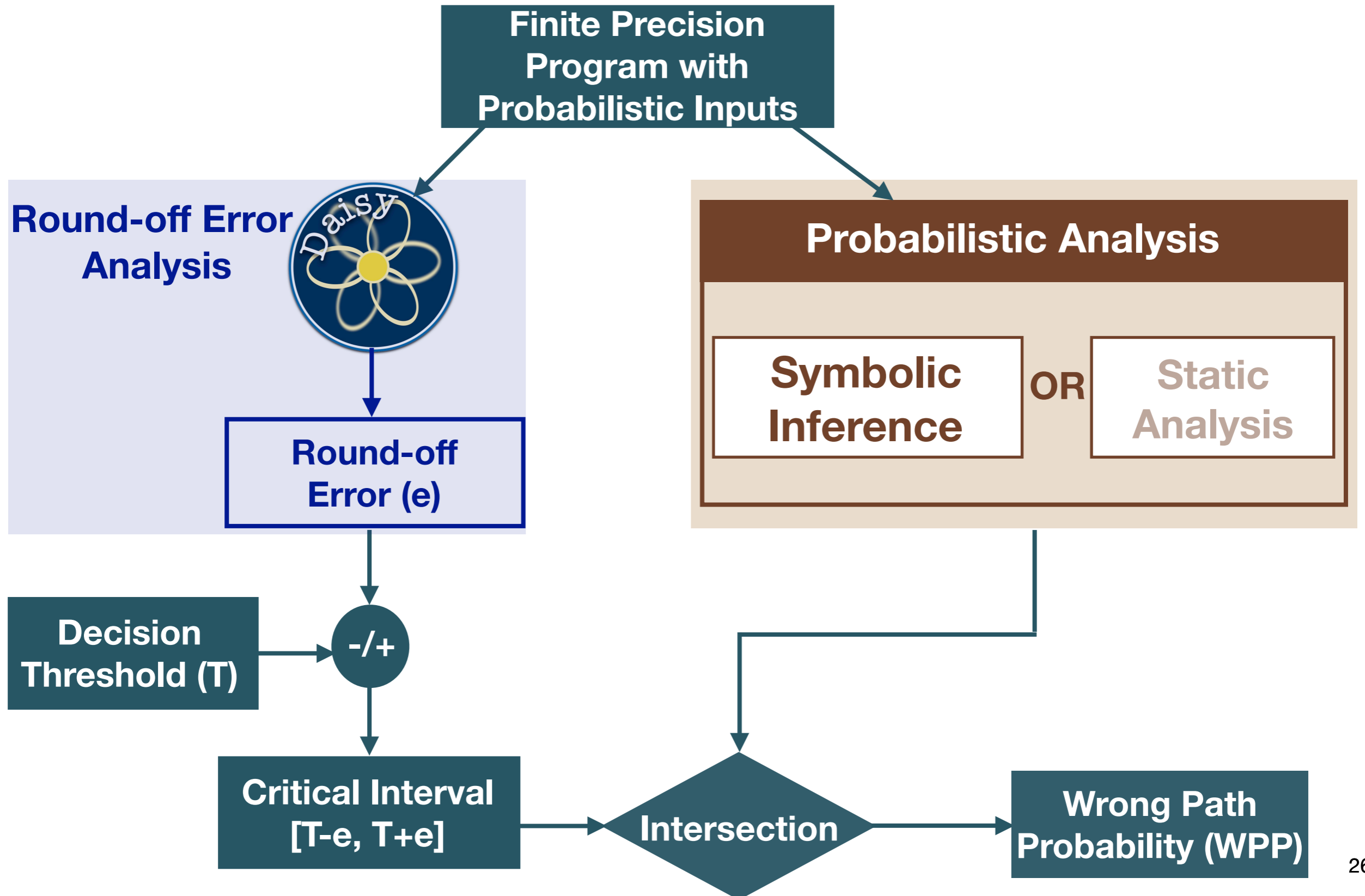
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  require (-15 <= x, y, z <= 15)  
  val res = -x*y - 2*y*z - x - z  
}
```

e in res = 1.73e-04

Distribution Propagation



Distribution Propagation



Symbolic Inference

Program + Critical
Interval as assert



Probabilistic
Symbolic Inference
(PSI)

```
def main() {  
  x:= uniform(-15.0, 15.0)  
  y:= uniform(-15.0, 15.0)  
  z:= uniform(-15.0, 15.0)  
  res:= -x*y - 2*y*z - x - z
```

```
//e: round-off error; T: decision threshold  
  assert(!(T-e <= res && res <= T+e))  
}
```

PSI considers uniform/normal independent inputs

Symbolic Inference

Program + Critical
Interval as assert

Probabilistic
Symbolic Inference
(PSI)

Exact
Distribution

```
def main() {  
  x:= uniform(-15.0, 15.0)  
  y:= uniform(-15.0, 15.0)  
  z:= uniform(-15.0, 15.0)  
  res:= -x*y - 2*y*z - x - z
```

```
//e: round-off error; T: decision threshold  
  assert(!(T-e <= res && res <= T+e))  
}
```

Computes probability distribution of the assertion failing

Symbolic Inference

Program + Critical
Interval as assert

Probabilistic
Symbolic Inference
(PSI)

Exact
Distribution

PSI computes the expression of exact WPP

$$-1 / (-1 / \text{Pi} * \text{Sqrt}[\text{Pi}] * (\text{Erf}[-1/2^{(1/2)}] + 1) / 2 * \text{Sqrt}[\text{Pi}] * (\text{Erf}[1/450^{(1/2)} * 15] + 1) \dots$$

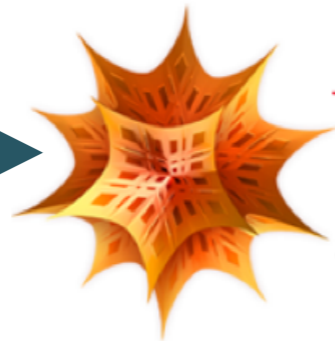
Symbolic Inference

Program + Critical
Interval as assert

Probabilistic
Symbolic Inference
(PSI)

Exact
Distribution

Mathematica numerically evaluates the distribution



Wolfram
Mathematica[®]

Wrong Path
Probability (WPP)

Symbolic Inference

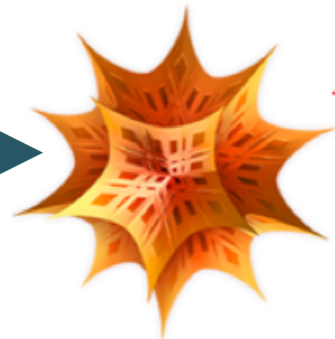
Program + Critical Interval as assert



Probabilistic Symbolic Inference (PSI)



Exact Distribution



Wolfram
Mathematica®



Wrong Path Probability (WPP)

```
def controller(x:Float32, y:Float32, z:Float32): Float32 = {  
  require (-15 <= x, y, z <= 15)  
  val res = -x*y - 2*y*z - x - z  
  if (res <= 0.0) raiseAlarm()  
  else doNothing()  
}
```

Symbolic Inference

Program + Critical Interval as assert



Probabilistic Symbolic Inference (PSI)

Exact Distribution

```
def controller(x:Float32, y:Float32, z:Float32): Float32 = {
```

Mathematica Timed Out!

```
  if (res <= 0.0) raiseAlarm()  
  else doNothing()  
}
```



Wolfram
Mathematica[®]



Wrong Path Probability (WPP)

Symbolic Inference

Program + Critical Interval as assert

```
def controller(x:Float32, y:Float32, z:Float32): Float32 = {
```

Timed out for many of the benchmarks

Symbolic Inference (PSI)

Exact Distribution



Wrong Path Probability (WPP)

WPP using Symbolic Inference

Benchmarks	#ops
sine	18
sqrt	14
turbine1	14
traincar2	13
doppler	10
bspline1	8
rigidbody1	7
traincar1	7
bspline0	6
sineorder3	4

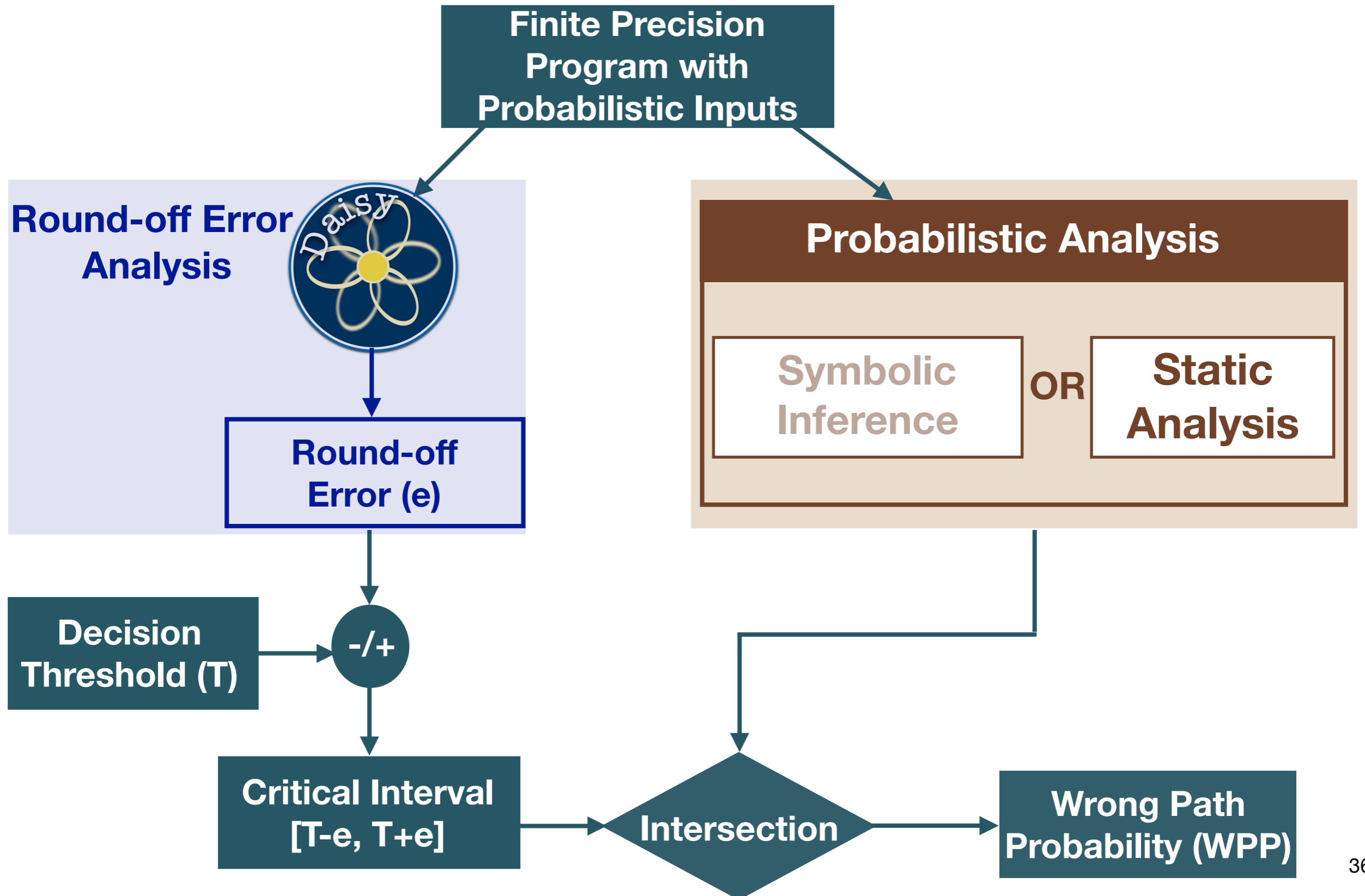
wrong path probability for 32 bit floating-point round-off errors and uniform input distributions

WPP using Symbolic Inference

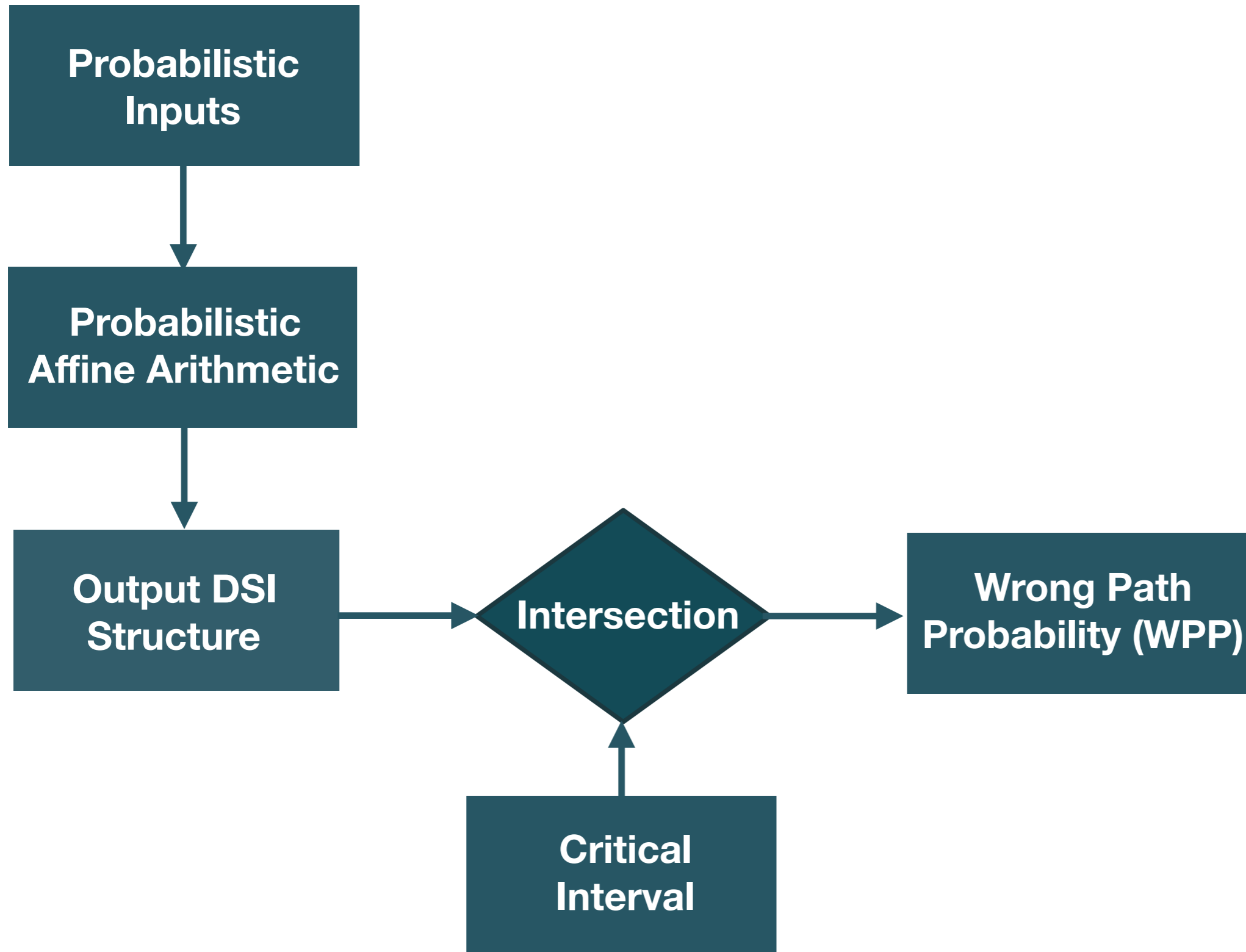
Benchmarks	#ops	Sym. Inf.
sine	18	7.61e-7
sqrt	14	8.74e-6
turbine1	14	TO
traincar2	13	TO
doppler	10	TO
bspline1	8	2.54e-6
rigidbody1	7	TO
traincar1	7	TO
bspline0	6	1.05e-5
sineorder3	4	1.90e-6

wrong path probability for 32 bit floating-point round-off errors and uniform input distributions

Distribution Propagation



Probabilistic Static Analysis



Probabilistic Static Analysis

Probabilistic
Inputs

Probabilistic Inputs as uncertain probabilities

Probabilistic
Affine Arithmetic

Probabilistic Affine Arithmetic propagates
the probabilities

Output DSI
Structure

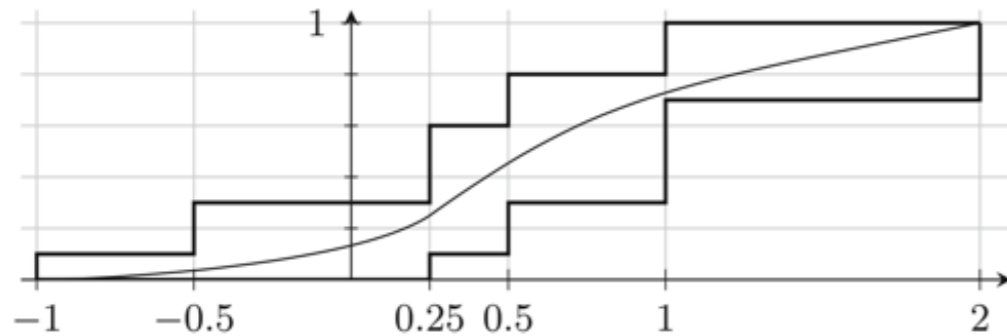
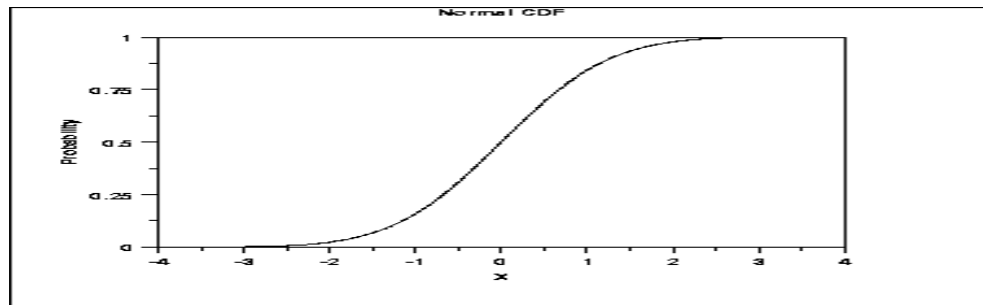
Intersection

Wrong Path
Probability (WPP)

Critical
Interval

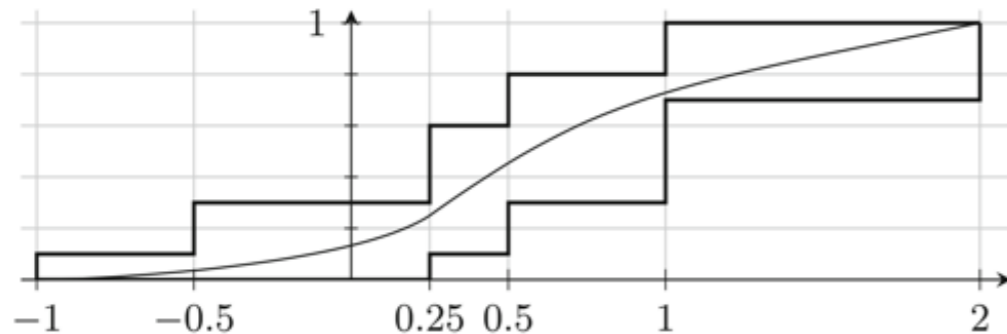
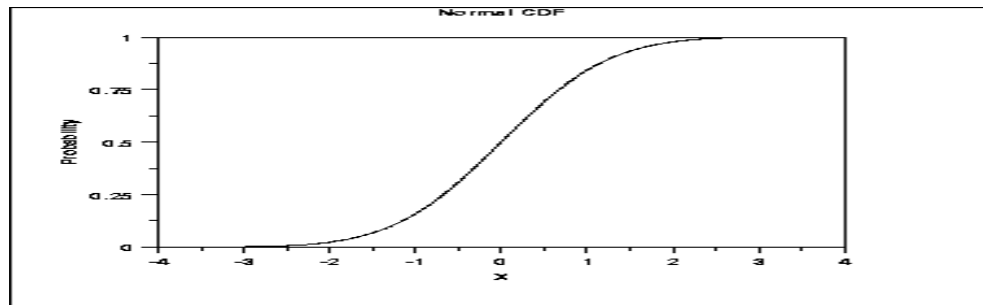
Dempster Shafer Interval (DSI) Structure

Discretizes the continuous distribution into sets of intervals and weights



Dempster Shafer Interval (DSI) Structure

Discretizes the continuous distribution into sets of intervals and weights



- Number of discretization is fixed
- Divides the input range



$\{ \langle [-1.0, -0.5], 0.1 \rangle, \langle [-0.5, 0.25], 0.2 \rangle, \dots \dots \dots \}$



Focal Element

Dempster Shafer Interval (DSI) Arithmetic

$$x \rightarrow d_x = \{ \langle [xa_i, xb_i], xw_i \rangle, i \in [1, n] \}$$

$$y \rightarrow d_y = \{ \langle [ya_j, yb_j], yw_j \rangle, j \in [1, m] \}$$

$$z = x \square y, (\square = +, -, \times, \div)$$

x, y are independent



- Interval arithmetic for intervals
- Weights are multiplied

Dempster Shafer Interval (DSI) Arithmetic

$$x \rightarrow d_x = \{ \langle [xa_i, xb_i], xw_i \rangle, i \in [1, n] \}$$

$$y \rightarrow d_y = \{ \langle [ya_j, yb_j], yw_j \rangle, j \in [1, m] \}$$

$$z = x \square y, (\square = +, -, \times, \div)$$

x, y are independent

x, y are dependent

- Interval arithmetic for intervals
- Weights are multiplied

- Interval arithmetic for intervals
- Simplex Solver to compute weights

Dempster Shafer Interval (DSI) Arithmetic

$$x \rightarrow d_x = \{ \langle [xa_i, xb_i], xw_i \rangle, i \in [1, n] \}$$

$$y \rightarrow d_y = \{ \langle [ya_j, yb_j], yw_j \rangle, j \in [1, m] \}$$

We need to track dependency

- Interval arithmetic for intervals
- Weights are multiplied

- Interval arithmetic for intervals
- Simplex Solver to compute weights

Probabilistic Affine Arithmetic

- Affine Arithmetic propagates linear relations between variables
- Dependencies are tracked using shared noise symbol

$$\hat{x} := x_0 + \sum_{i=1}^p x_i \epsilon_i, \quad \epsilon_i \in [-1, 1]$$

↓
Noise Symbol

Probabilistic Affine Arithmetic

- Affine Arithmetic propagates linear relations between variables
- Dependencies are tracked using shared noise symbol
- Uses DSI to keep the probabilities while tracking dependencies

$$\hat{x} := x_0 + \sum_{i=1}^p x_i \epsilon_i, \epsilon_i \in [-1, 1]$$

DSI $d_x : \langle [a_1, b_1], w_1 \rangle, \dots, \langle [a_n, b_n], w_n \rangle$
↑
Noise Symbol
↓

Probabilistic Affine Arithmetic

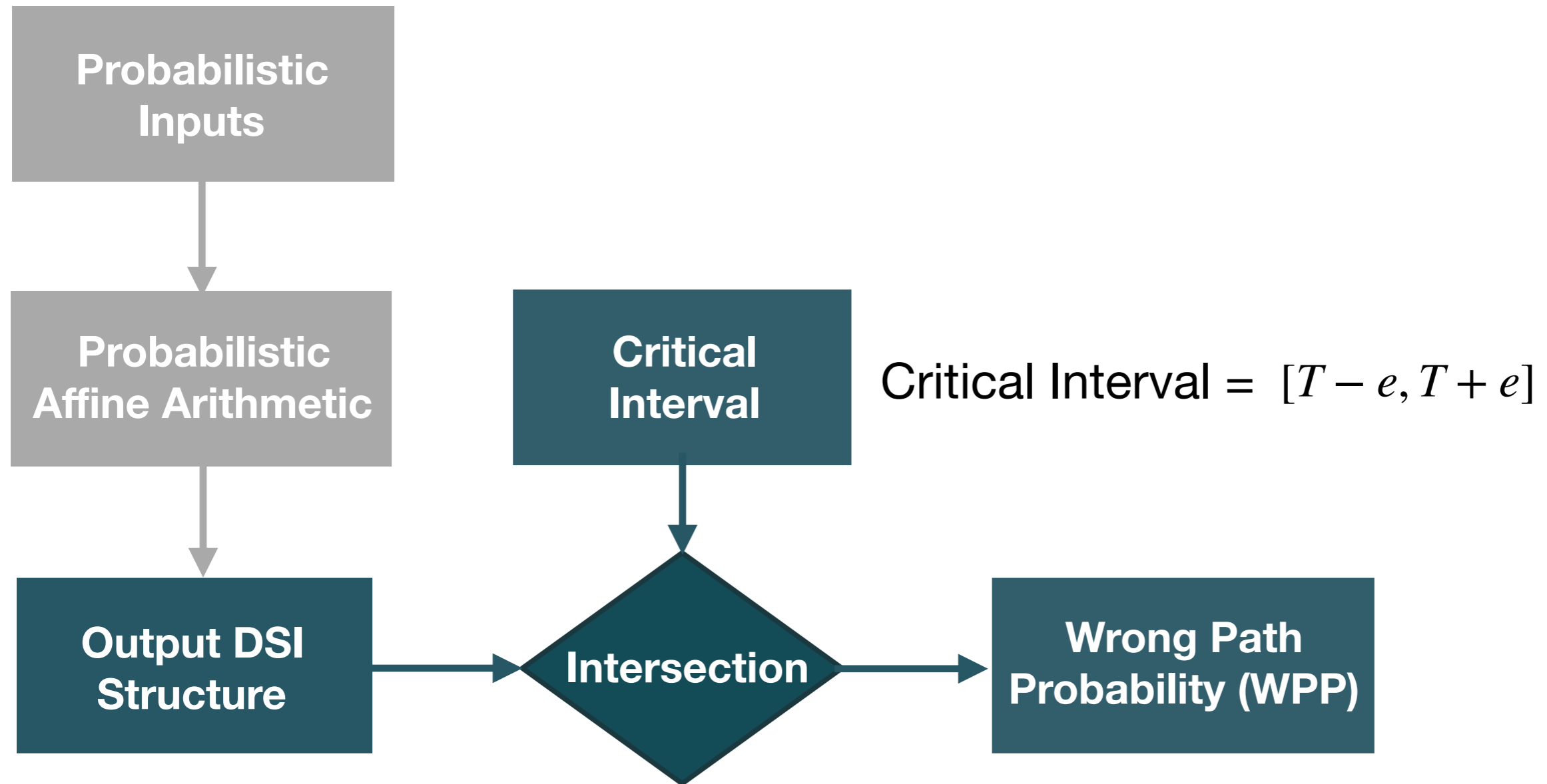
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DSI $d_x : \langle [a_1, b_1], w_1 \rangle, \dots, \langle [a_n, b_n], w_n \rangle$
↑
Noise Symbol

- Arithmetic operations are computed term wise

Probabilistic Static Analysis




$$\text{Output DSI} = d_x : \langle [a_1, b_1], w_1 \rangle, \dots, \langle [a_n, b_n], w_n \rangle$$

Intersection

Critical Interval —

$$[T - e, T + e]$$


$$w_6 = 0.05$$


$$w_5 = 0.35$$


$$w_4 = 0.1$$


$$w_3 = 0.2$$


$$w_2 = 0.1$$


$$w_1 = 0.2$$

Output DSI

$$\langle [a_n, b_n], w_n \rangle$$

·

·

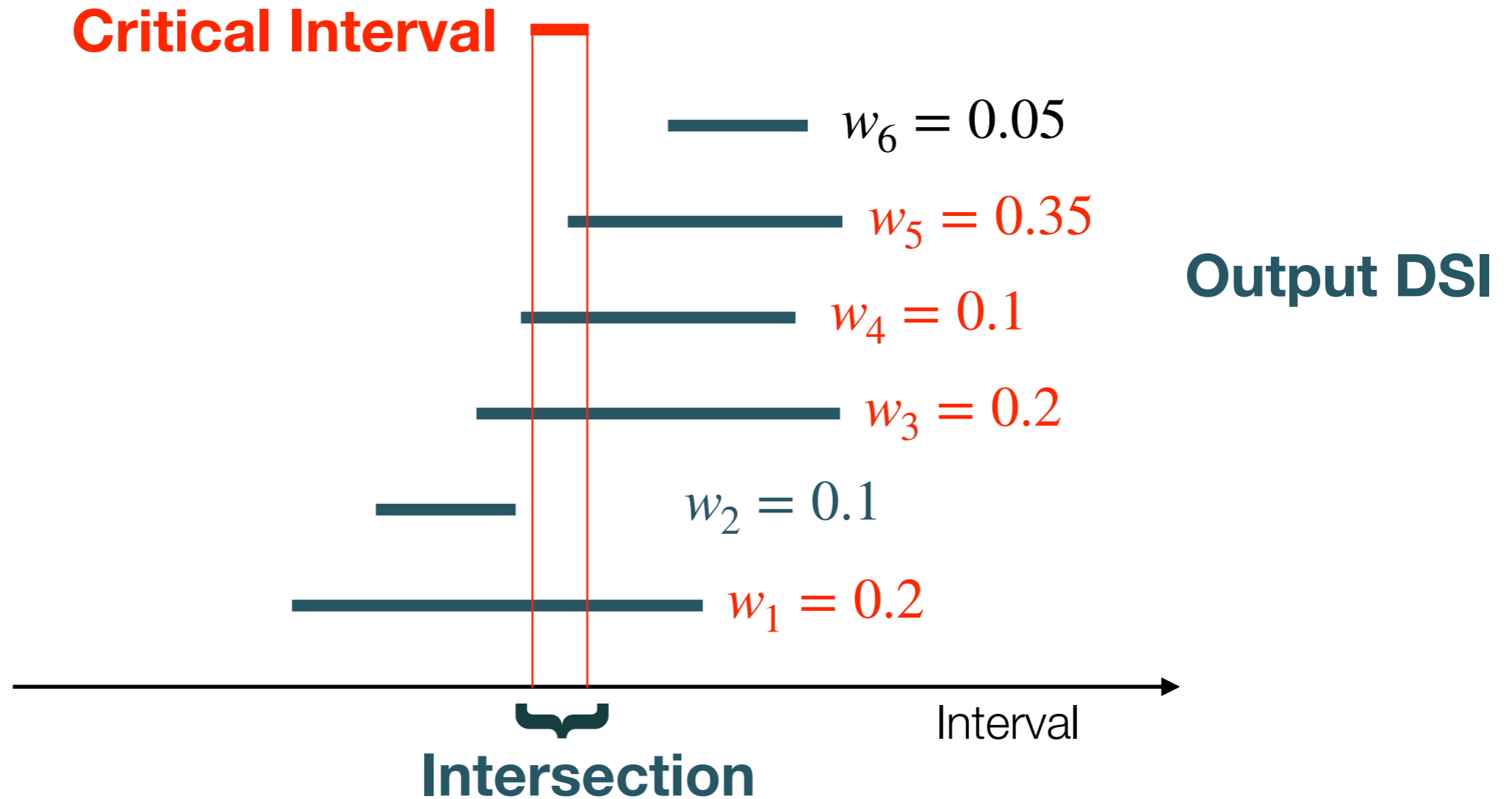
·

·

$$\langle [a_1, b_1], w_1 \rangle$$

Interval →

Intersection



$$\begin{aligned} \text{Wrong Path Probability} &= 0.2 + 0.2 + 0.1 + 0.35 \\ &= 0.85 \end{aligned}$$

Probabilistic Static Analysis

Probabilistic
Inputs

In general incurs huge overapproximation

Output DSI
Structure

Intersection

Wrong Path
Probability (WPP)

Probabilistic Static Analysis

Probabilistic
Inputs

In general incurs huge overapproximation

Output DSI
Structure

```
def controller(x:Float32,y:Float32,  
z:Float32): Float32 = {  
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  if (res <= 0.0) raiseAlarm()  
  else doNothing()  
}
```

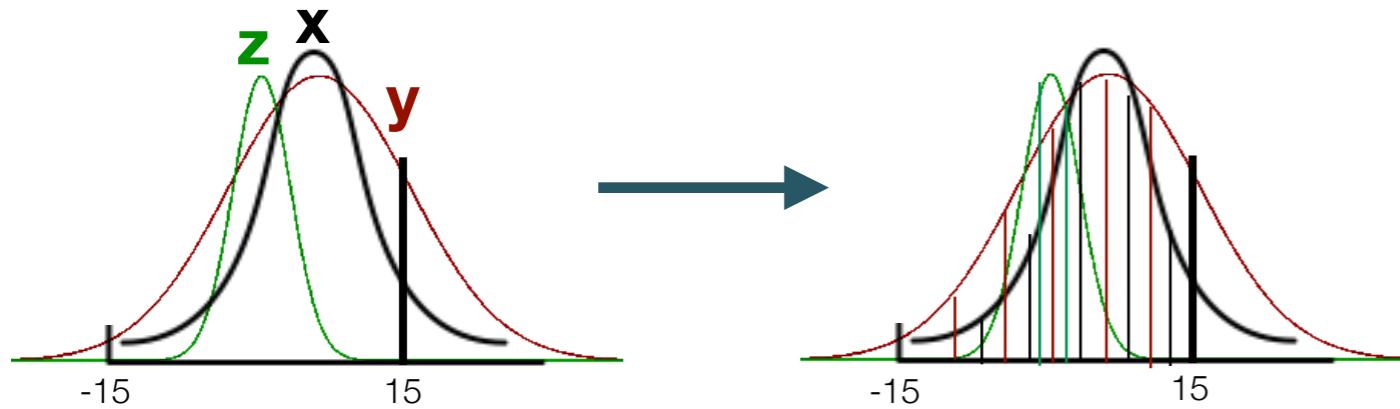
WPP = 1.0

WPP using Probabilistic Static Analysis

Benchmarks	#ops	Sym. Inf.	Probabilistic
sine	18	7.61e-7	0.32
sqrt	14	8.74e-6	1.00
turbine1	14	TO	1.00
traincar2	13	TO	0.11
doppler	10	TO	1.00
bspline1	8	2.54e-6	0.96
rigidbody1	7	TO	1.00
traincar1	7	TO	0.10
bspline0	6	1.05e-5	1.00
sineorder3	4	1.90e-6	0.36

wrong path probability for 32 bit floating-point round-off errors and uniform input distributions

Interval Subdivision



Input
Intervals

n subdivided
Intervals

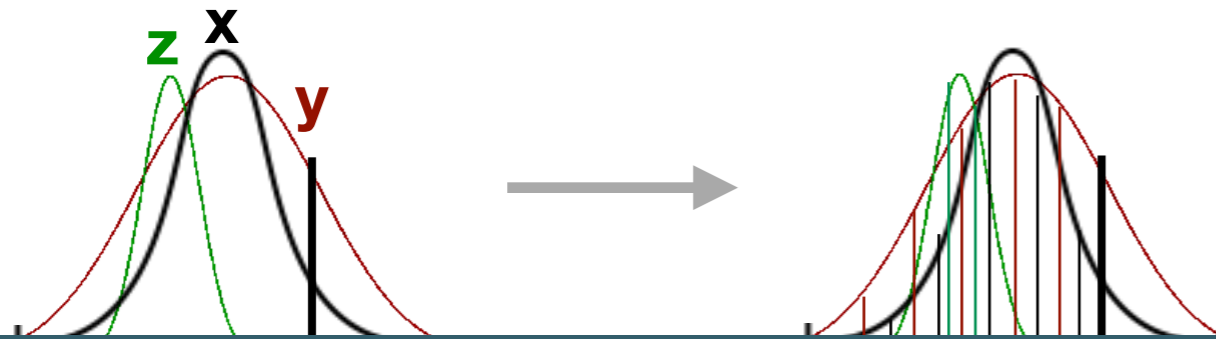
subdomains
 $s_{ijk} = x_i \times y_j \times z_k$

Total WPP =

$$\rho_{total} = \sum_{i=1}^n Prob(s_{ijk}) \rho_{ijk}$$

$\rho_{ijk} \leftarrow$ Probabilistic
Analysis

Interval Subdivision

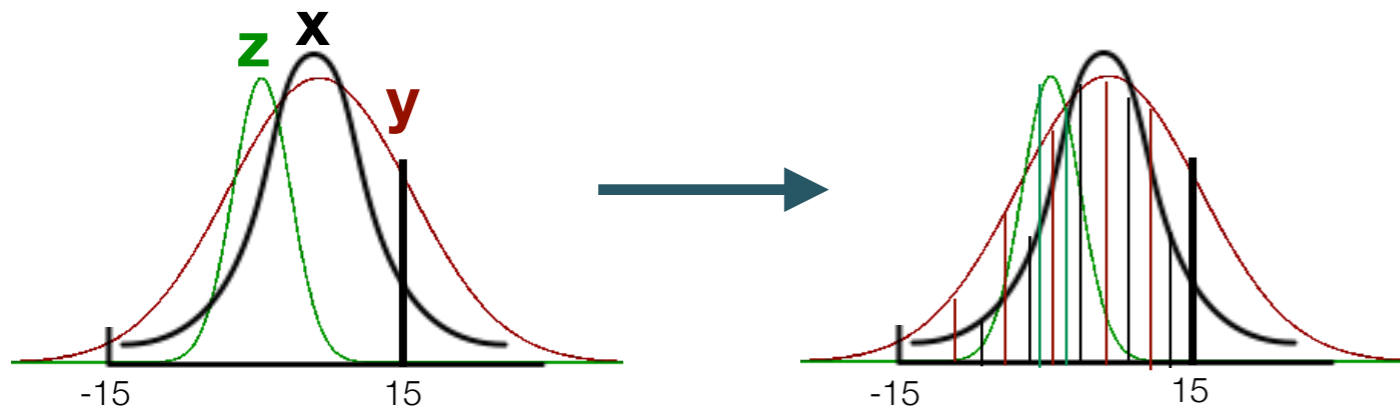


Probabilistic Analysis is costly

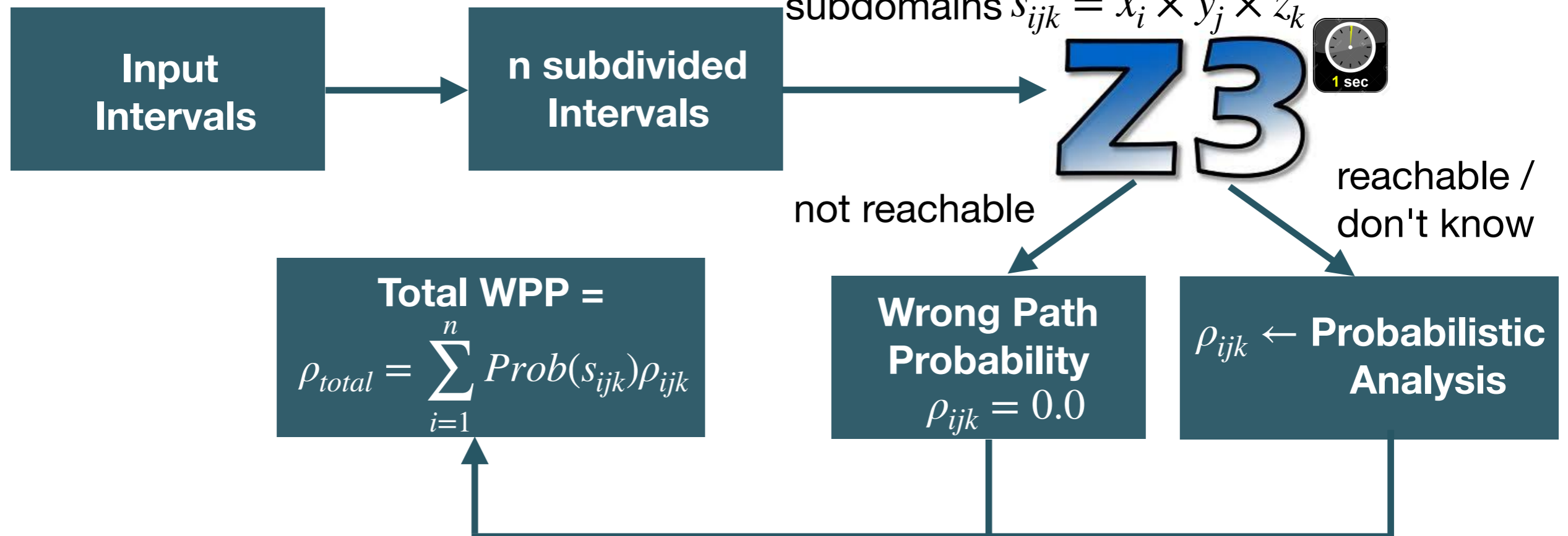
$$\text{Total WPP} = \rho_{total} = \sum_{i=1}^n \text{Prob}(s_{ijk}) \rho_{ijk}$$

$\rho_{ijk} = \text{Probabilistic Analysis}$

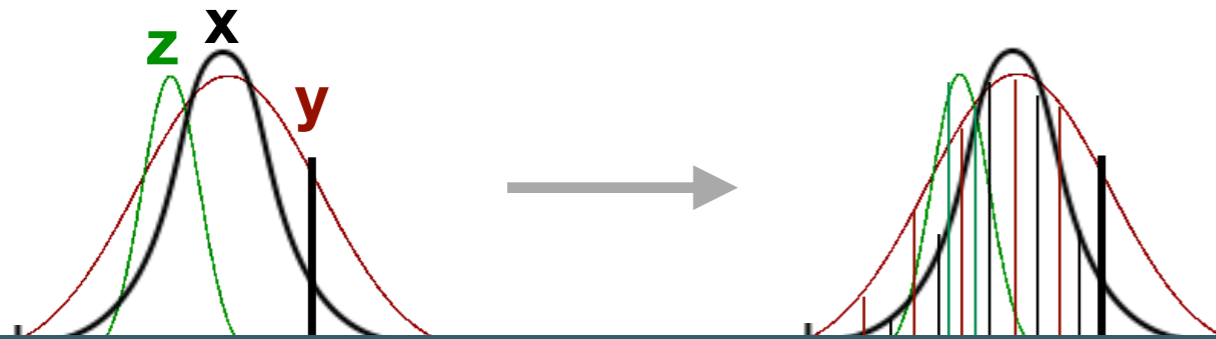
Pruning subdomains by reachability checks



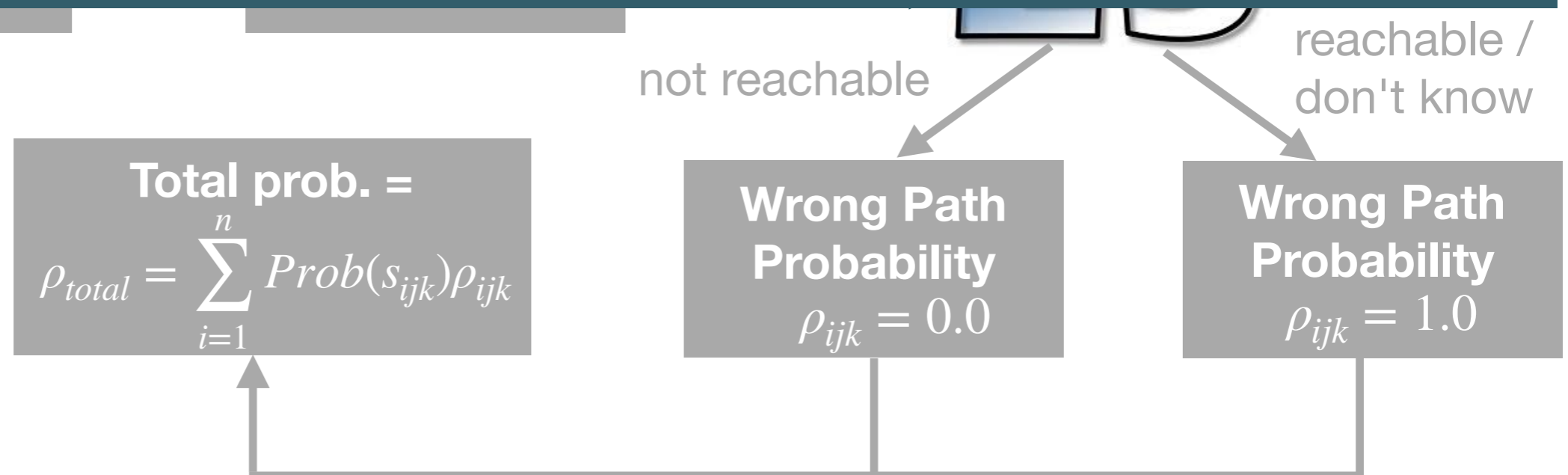
Is the critical interval reachable?



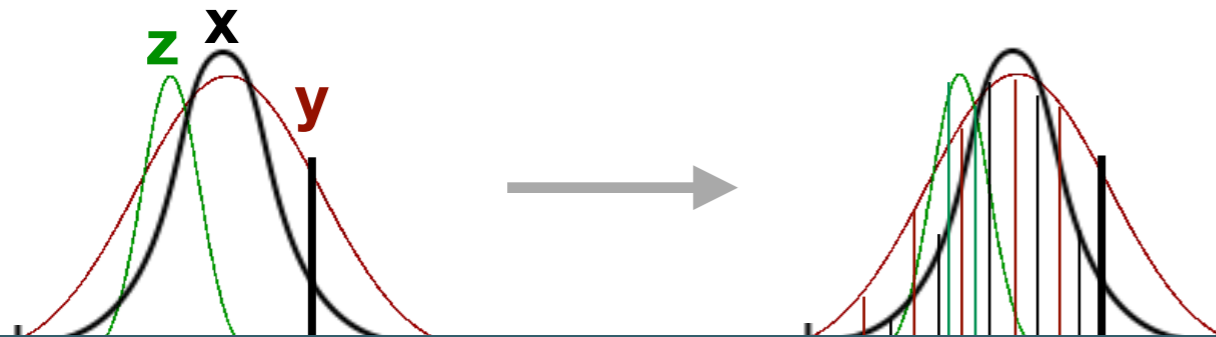
Interval Subdivision + Reachability



No. of subdomain: 8000
No. of DSI discretization: 4



Interval Subdivision + Reachability



Provides good estimates

```
def controller(x:Float32,y:Float32,
z:Float32): Float32 = {
  require (-15 <= x, y, z <= 15)
  val res = -x*y - 2*y*z - x - z
  if (res <= 0.0) raiseAlarm()
  else doNothing()
}
```

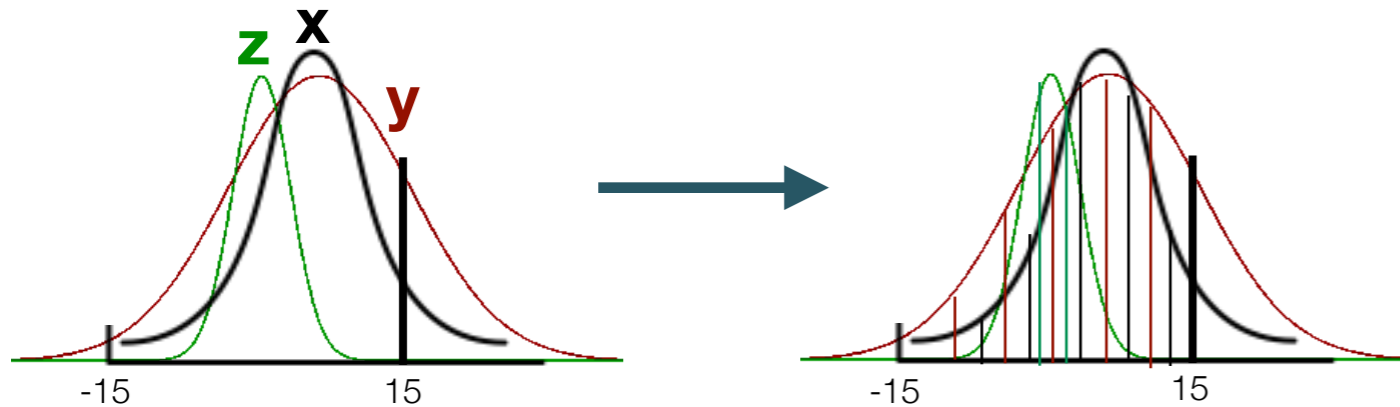
ρ_{total}

WPP = 4.39e-3

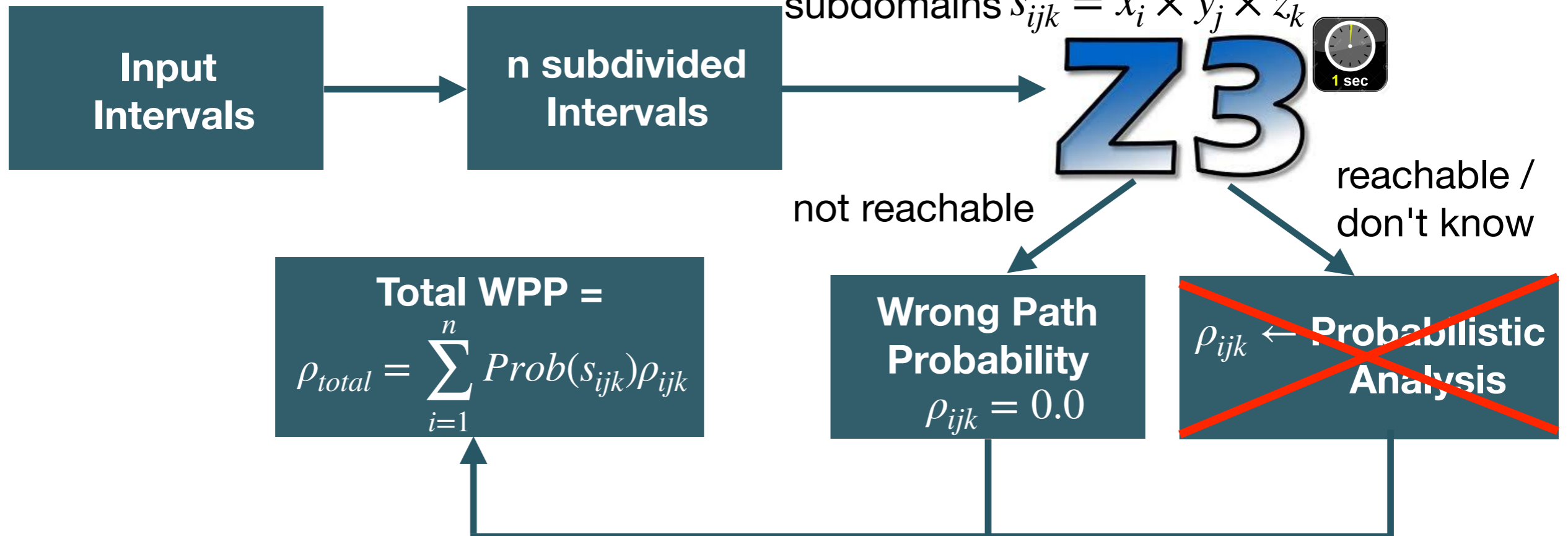
reachable /
don't know

Probabilistic
Analysis

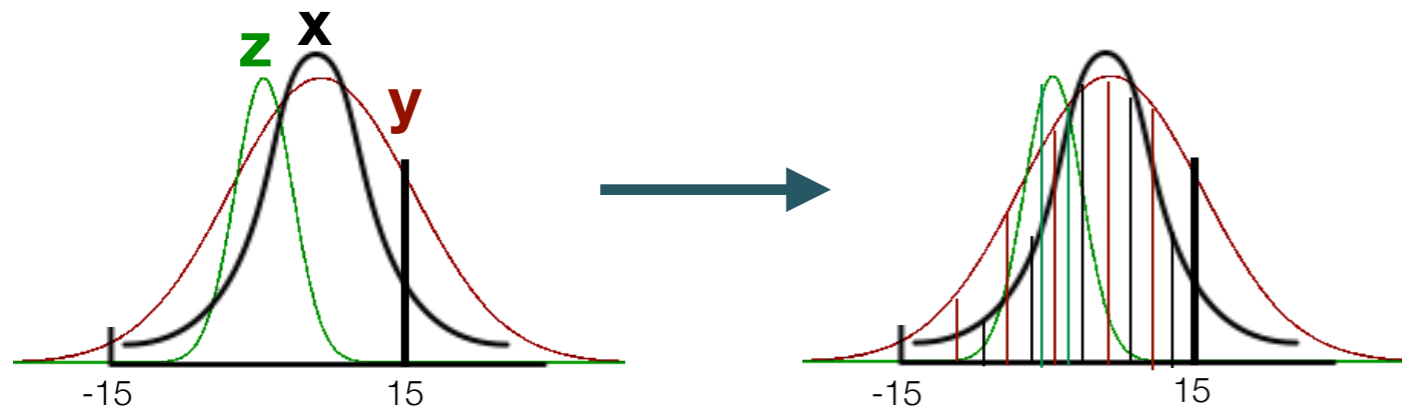
Can we skip the Probabilistic Analysis?



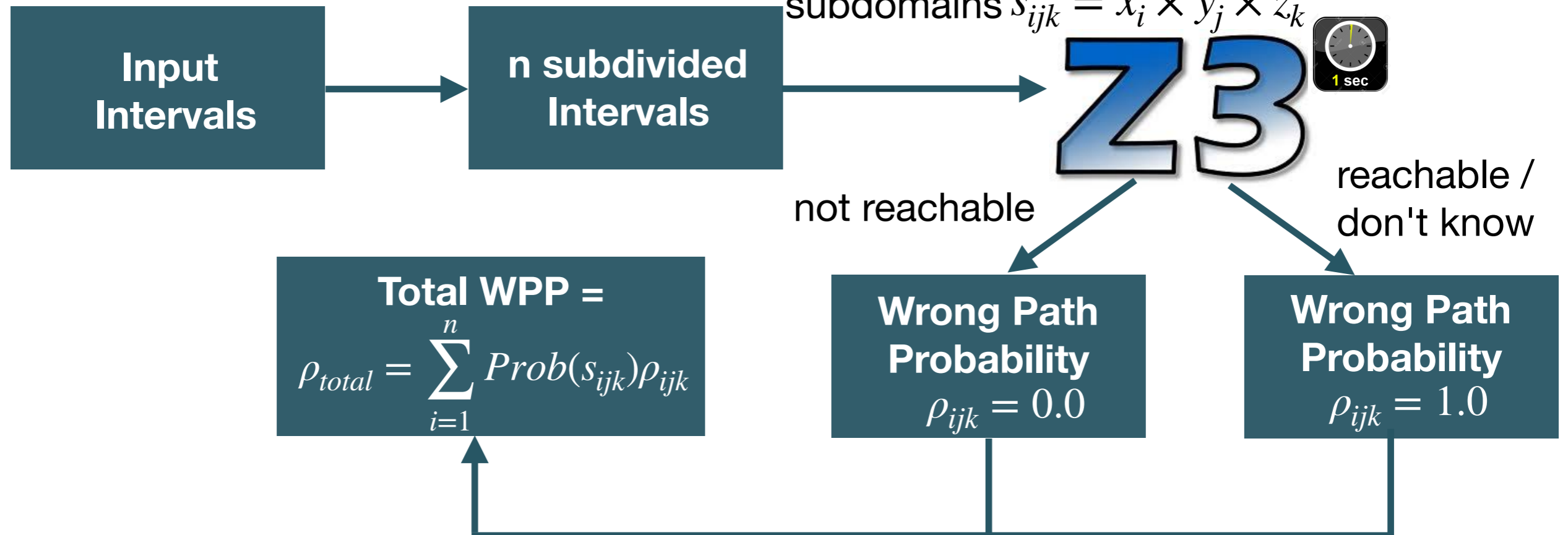
Is the critical interval reachable?



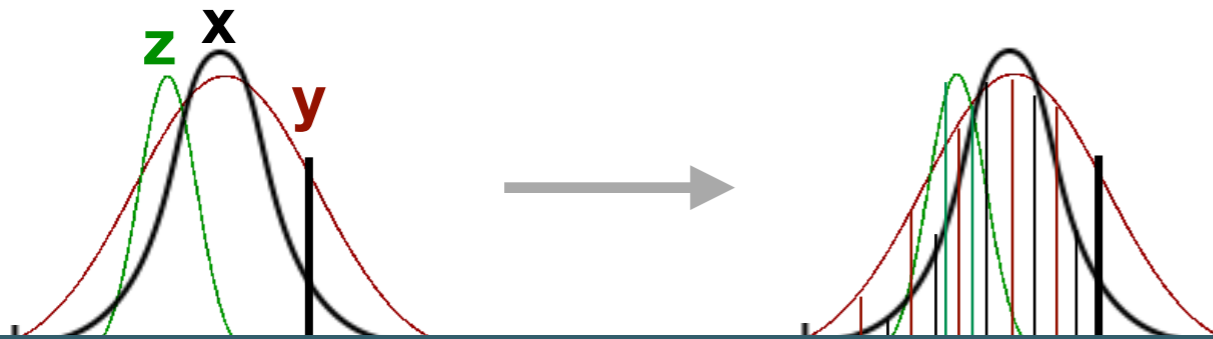
Non-Probabilistic Analysis



Is the critical interval reachable?



Non-Probabilistic Analysis



Works well for univariate functions

```
def controller(x:Float32,y:Float32,
z:Float32): Float32 = {
  require (-15 <= x, y, z <= 15)
  val res = -x*y - 2*y*z - x - z
  if (res <= 0.0) raiseAlarm()
  else doNothing()
}
```

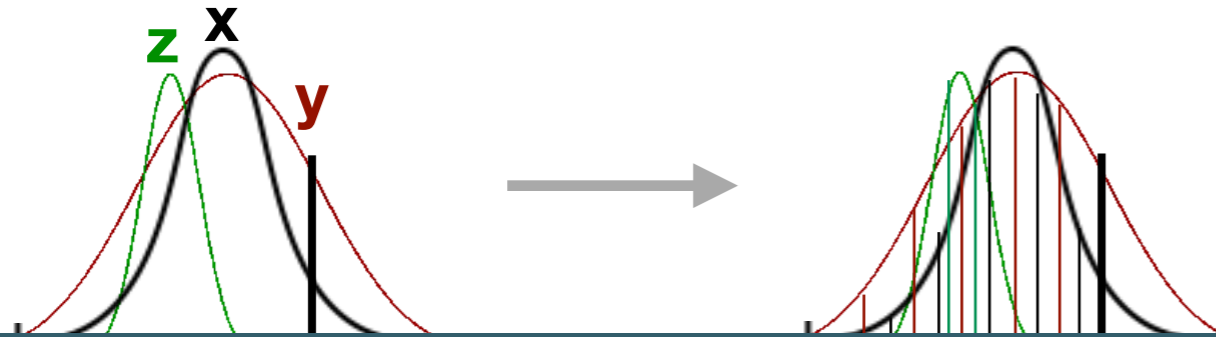
ρ_{to}

WPP = 2.53e-2

reachable /
don't know

Wrong Path
Probability
 $\rho_{ijk} = 1.0$

Non-Probabilistic Analysis



No. of subdomain: 32000

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```

ρ_{total}

reachable /
don't know

Wrong Path
Probability
 $\rho_{ijk} = 1.0$

WPP = $2.53e-2 > 4.39e-3$

WPP using Probabilistic Analysis with Subdiv

Benchmarks	#ops	Sym. Inf.	Probabilistic	Probabilistic with Subdiv
sine	18	7.61e-7	0.32	6.45e-5
sqrt	14	8.74e-6	1.00	9.38e-5
turbine1	14	TO	1.00	4.82e-2
traincar2	13	TO	0.11	9.17e-2
doppler	10	TO	1.00	2.17e-2
bspline1	8	2.54e-6	0.96	1.95e-5
rigidbody1	7	TO	1.00	7.06e-2
traincar1	7	TO	0.10	1.86e-2
bspline0	6	1.05e-5	1.00	6.06e-5
sineorder3	4	1.90e-6	0.36	1.23e-4

wrong path probability for 32 bit floating-point round-off errors and uniform input distributions

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Case Studies

Case Studies from **embedded systems** and **machine learning**

└─ filter
└─ traincar

└─ Simplified DNN
└─ Linear SVC

It scales for real world programs!

What else is there in the paper?

Extensive experiments on

- ~ Fixed precision vs Floating-point precision
- ✓ Uniform vs Gaussian distributions
- ✓ Dependent vs Independent inputs

"Discrete Choice in the Presence of Numerical Uncertainties"

D. Lohar, E. Darulova, S. Putot and E. Gobault

Conclusion

- Sound Analysis of Numerical Uncertainties on Decisions
- **Probabilistic Symbolic Inference** suffers from **scalability issues**
- **Probabilistic Static Analysis** has **accuracy issues**
- **Static analysis with reachability** is **accurate** and **scalable**

